

Gemini is a new line of fieldbus vector drives characterised by innovative performance; these drives allow to command BLDC motor with less heating and extremely smooth movements. Suitable for driving 3-phase BLDC motors, they can be coupled mainly with the series of motors up to 400 Watt.. Completely digital and made using Arm Core M4 technology, Gemini drives offer exceptional reliability combined with mechanical compactness and a competitive price. They can be used in many types of machines where there is already a fieldbus master controller to control single or multi-axle systems. Their use is of the 'general purpose' type and they are particularly suitable in conveyors, robot arms, separators etc.



Principal features

- 1 Multiple control modes: analog, Ethercat, Modbus TCP, Canopen or programmable
- 2 Equipped with advanced safety features such as integrated diagnostic and separated power supply for logic and power fault monitoring and Handling
- 3 Motion controller on board
- 4 Vector control: the sinusoidal regulation allowing smooth and silent movements
- 5 Closed loop through encoder or hall sensors
- 6 Compact sizes
- 7 Auto tuning of motor control parameters
- 8 High efficiency current set up

Functions

- 1 Velocity control mode
- 2 Wide range of Positioning Control Modes (homing, relative, absolute, target)
- 3 Electric Gear with programmable gear ratio to track external master reference (from fieldbus or incremental encoder) of motor Speed and Position
- 4 High speed I/O triggered motor start & stop to event synchronizing for fast response demanding application: labeling, nick_finder, on fly cut., etc ...
- 5 Multi Axis movements synchronization capability
- 6 On fly change among any Motion Module Control Mode
- 7 On fly Electric Gear Enable/Disable capability
- 8 Closed Loop of torque, speed and position through encoder.

Technical Data

Driver Type

Brushless DC Motors

Interface control mode

Modbus RS 485
CANopen
Ethernet ModBus TCP
Ethercat

Electrical data

| | |
|-------------------------------------|--------------------------------------|
| Operating voltage (min.) | 12 [Vcc] |
| Operating voltage (max.) | 48 [Vdc] |
| Separated logic power supply (min.) | 12 [Vcc] |
| Separated logic power supply (max.) | 48 [Vdc] |
| Phase Current | up to 10Arms (28 Apeak for 5 second) |
| Motor Power | up to 400W |
| Chopper Frequency: | Ultrasonic 40KHz |

Operating Modes

profile position mode, velocity mode, homing mode, cyclic sync position mode, cyclic sync velocity mode, cyclic sync torque mode, clock direction mode, service SCI interface for programming and real time debugging.

Inputs

| | |
|--------------------|---|
| Digital inputs | 6 Digital inputs: Opto-coupled |
| Hall sensor inputs | 5V Single-Ended (TTL/CMOS) hall effects |
| Encoder Inputs | 5V Differential (RS422) or 5V Single-Ended (TTL/CMOS) incremental encoder |

Output

| | |
|-----------------|---|
| Digital outputs | 2 optoisolated: PNP, 24 Vdc - 100 mA - 1kHz |
|-----------------|---|

Protective functions

Over/UnderVoltage, OverCurrent, OverTemperature, Phase/Phase and Phase/Ground Short

Mechanical Data

| | |
|--------------------|------------------------------------|
| Weight | 150 g |
| Dimension (length) | 84.5 [mm] |
| Dimension (width) | 30 [mm] |
| Dimension (height) | 139 [mm] |
| Protection class | IP20 |
| Status monitoring | 4 LED (green, blue,yellow and red) |

Ambient conditions

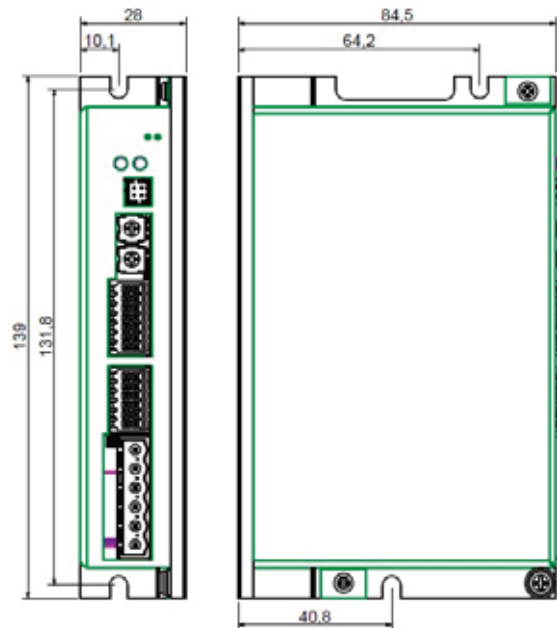
| | |
|----------------------------------|----------|
| Temperature – Operation (min.) | 0 [°C] |
| Temperature – Operation (max.) | 40 [°C] |
| Temperature – Storage (min.) | -25 [°C] |
| Temperature – Storage (max.) | 55 [°C] |
| Humidity (non-condensing) (min.) | 5 [%] |
| Humidity (non-condensing) (max.) | 85 [%] |

Software

| | |
|-------------------------|------------|
| Setup and configuration | E&D Studio |
| Programming | E&D Space |

Version

| | Power Supply Voltage | | Output Current | | | Interface Control Mode | Open or Close Loop |
|------------------|----------------------|------|----------------|------|-------------|-------------------------|--------------------|
| | Vcc. | | [A/ph rms] | | [A/ph peak] | | |
| | Min. | Max. | Min. | Max. | Max. | | |
| B400B30T001-S200 | 12 | 48 | 0.0 | 10 | 28 | Ethernet Modbus TCP | Close Loop |
| B400B30E001-S402 | 12 | 48 | 0.0 | 10 | 28 | EtherCAT CoE (DS402) | Close Loop |
| B400B30C001-S402 | 12 | 48 | 0.0 | 10 | 28 | CANopen (DS402) | Close Loop |
| B400B30C001-S200 | 12 | 48 | 0.0 | 10 | 28 | CANopen (Programmable) | Close Loop |
| B400B30M001-S200 | 12 | 48 | 0.0 | 10 | 28 | Serial RS485 Modbus-RTU | Close Loop |



Product Combination

| Code | Size (mm) | Rated Speed (rpm) | Rated Torque (Nm) | Page |
|------------------|-----------|-------------------|-------------------|------|
| BL42061-026E.000 | 26 | 4.000 | 0,062 | 32 |
| BL42081-050E.000 | 50 | 4.000 | 0,125 | 32 |
| BL42101-074E.000 | 74 | 4.000 | 0,185 | 32 |
| BL42121-100E.000 | 100 | 4.000 | 0,250 | 32 |
| BL57096-090E.000 | 90 | 3.000 | 0,300 | 34 |
| BL57116-135E.000 | 135 | 3.000 | 0,450 | 34 |
| BL57136-180E.000 | 180 | 3.000 | 0,600 | 34 |
| BL86080-130E.000 | 130 | 3.000 | 0,400 | 36 |
| BL86093-250E.000 | 250 | 3.000 | 0,800 | 36 |
| BL86121-500E.000 | 500 | 3.000 | 1,600 | 36 |